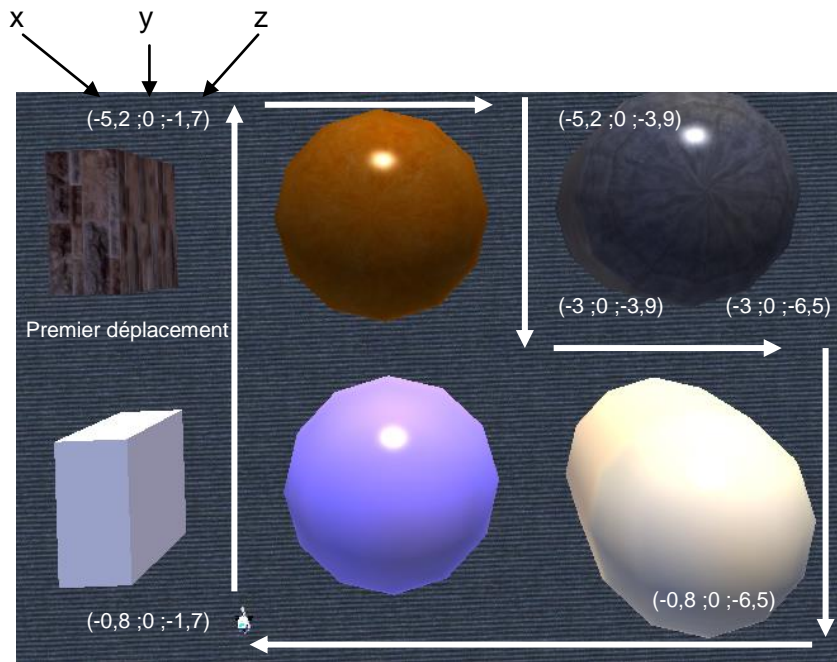


Q1)



| Déplacement | Action | Données | | | Détail du calcul de <i>Distance</i> |
|-------------|---------------|---------|------------|-------------|-------------------------------------|
| | | Power | Degrees(°) | Distance(m) | |
| 1 | DriveDistance | 0.5 | | 4.4 | $Dx = -5,2 - (-0,8) = 4.4$ |
| | RotateDegrees | 0.3 | -90 | | |
| 2 | DriveDistance | 0.5 | | 2.2 | $Dz = -3,9 - (-1,7) = 2.2$ |
| | RotateDegrees | 0.3 | -90 | | |
| 3 | DriveDistance | 0.5 | | 2.2 | $Dx = -3 - (-5,2) = 2.2$ |
| | RotateDegrees | 0.3 | 90 | | |
| 4 | DriveDistance | 0.5 | | 2.6 | $Dz = -6,5 - (-3,9) = 2.6$ |
| | RotateDegrees | 0.3 | -90 | | |
| 5 | DriveDistance | 0.5 | | 2.2 | $Dx = -0,8 - (-3) = 2.2$ |
| | RotateDegrees | 0.3 | -90 | | |
| 6 | DriveDistance | 0.5 | | 4.8 | $Dz = -1,7 - (-6,5) = 4.8$ |
| | RotateDegrees | 0.3 | -90 | | |

Q2)

